

Principal-Agent Games of Optimal Stopping

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Joint Work in Progress with **Emanuel Rapsch** (TU Berlin).



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- ▷ Irreversible investment under uncertainty and with competition
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Transition from internal combustion engine vehicles to battery-electric vehicles.

More precisely:

- ▷ Irreversible investment under uncertainty and with competition
→ **Game of Optimal Stopping**
- ▷ Optimal policy design to accelerate the transition
→ **Principal-Agent Problem** with **Asymmetric Information**

Economic Background

European Green Deal:

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- ▷ Transition from internal combustion engine vehicles to new energy vehicles
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- ▷ But: Consumer demand will grow with time

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The Irreversible Investment Problem

Consumer Preferences: Wright-Fischer Diffusion

$$dX_t = \mu X_t(1 - X_t)dt + \sigma \sqrt{X_t(1 - X_t)}dW_t$$

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- ▷ Can be generalized...

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$$J_1(x, z, \tau_1, \tau_2) = \mathbb{E}_{x,z} \left[\int_0^{\tau_1} e^{-\rho_1 t} \tilde{h}_1(X_t, Z_t^2, \alpha) dt + e^{-\rho_1 \tau_1} \tilde{f}_1(\alpha) \right. \\ \left. + \int_{\tau_1}^{\infty} e^{-\rho_1 t} \tilde{g}_1(X_t, Z_t^2, \alpha) dt \right]$$

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- Instead of pairs of stopping times (τ_1, τ_2) , our controls are $D_1(z)$ and $D_2(z)$ for $z \in \{0, 1\}$, where

$$D_1(0), D_1(1), D_2(0), D_2(1) \quad \text{are closed subsets of} \quad [0, 1].$$

Characterization of Equilibria I

Suppose that $D_1(z), D_2(z)$ are optimal and denote the corresponding value functions by v_1, v_2 . Then, for $i, j \in \{1, 2\}$ with $i \neq j$, it holds that

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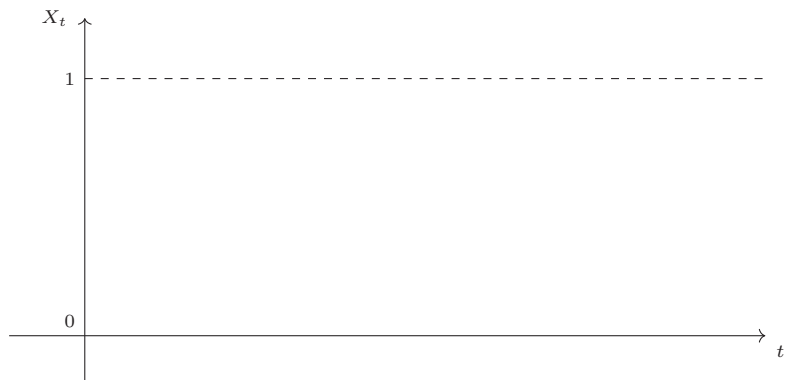
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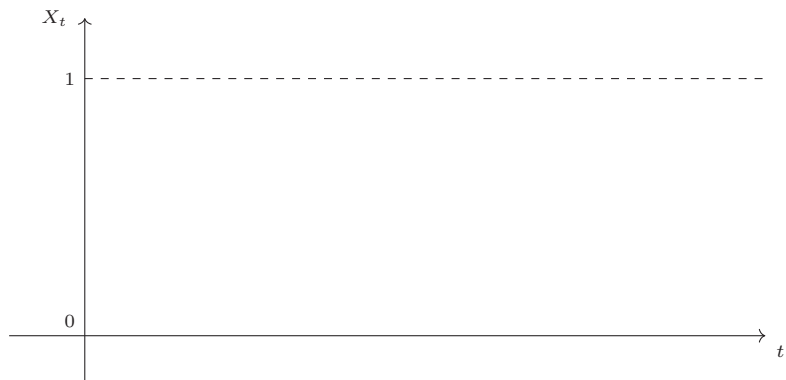
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Then D_1, D_2 are optimal.

Example 1:



Example 2:



The Principal-Agent Problem

The Principal:

- ▷ Influences the reward structure of the agents:

$$\alpha \mapsto J_1^\alpha(x, z, \tau_1, \tau_2) = \mathbb{E}_{x,z} \left[\int_0^{\tau_1} e^{-\rho_1 t} \tilde{h}_1(X_t, Z_t^i, \alpha) dt + e^{-\rho_1 \tau_1} \tilde{f}_1(\alpha) \right. \\ \left. + \int_{\tau_1}^{\infty} e^{-\rho_1 t} \tilde{g}_1(X_t, Z_t^2, \alpha) dt \right].$$

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- ▷ The policymaker benefits from a quick transition, but actions are costly.
- ▷ How to quantify response of the agents to a policy in the absence of uniqueness of Nash equilibria?

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- ▶ Otherwise, one has to replace the expectation in J_0 by a more general preference relation.

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Optimal Policies

The mapping

$$\alpha \mapsto J_0(x, z_1, z_2, \alpha, \tau_1^\alpha, \tau_2^\alpha)$$

is continuous and hence there exists an optimal $\alpha^* = \alpha^*(x, z_1, z_2) \in \mathbb{A}$.

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- ▷ Numerical experiments with realistic data seem to indicate that first-movers are usually the largest agents or risk-seeking newcomers.
- ▷ Results appear to be quite sensitive to the choice of discount factors.
- ▷ Plethora of different effects, especially due to the non-uniqueness of equilibria.

Conclusion:

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Thanks and Good Night!