

Non-Smooth Verification for Impulse Control Problems

Christoph Belak

Department IV – Mathematics
University of Trier
Germany

Joint work with **Sören Christensen** (Hamburg) and **Frank Seifried** (Trier).

Optimal Stopping in Complex Environments Workshop
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Outline

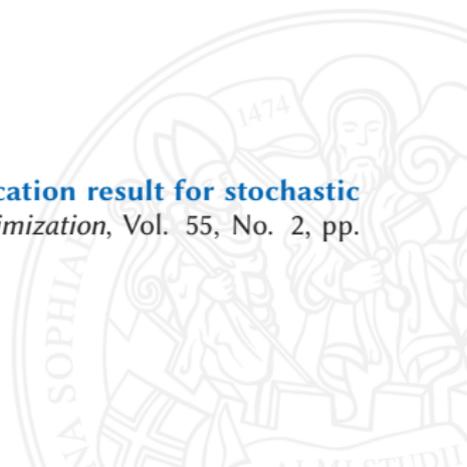
- (1) A New Approach to Impulse Control Problems
- (2) Utility Maximization with Constant Costs
- (3) (Dis-)Continuity of the Value Function



Stochastic Impulse Control Problems

Based on:

Belak, C., Christensen, S., and Seifried, F. T.: **A general verification result for stochastic impulse control problems**, *SIAM Journal on Control and Optimization*, Vol. 55, No. 2, pp. 627-649, 2017.



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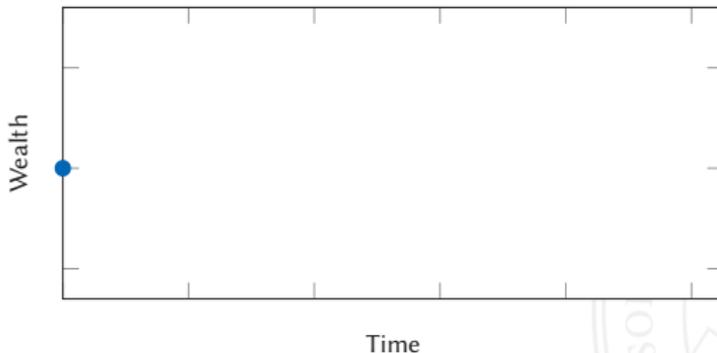


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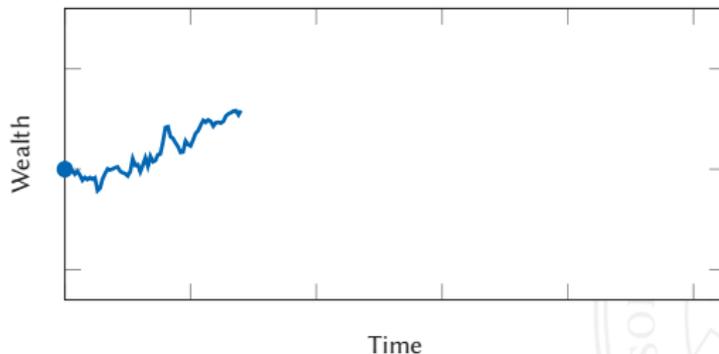


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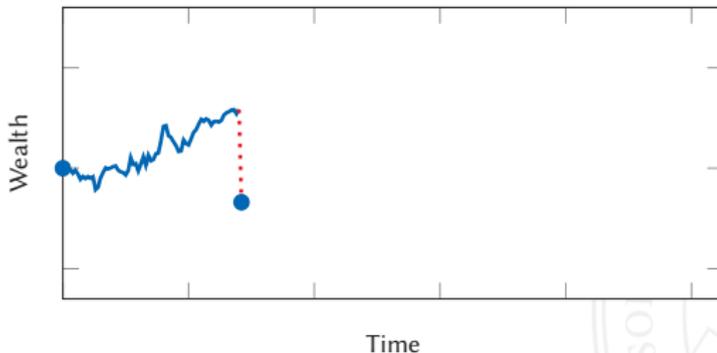


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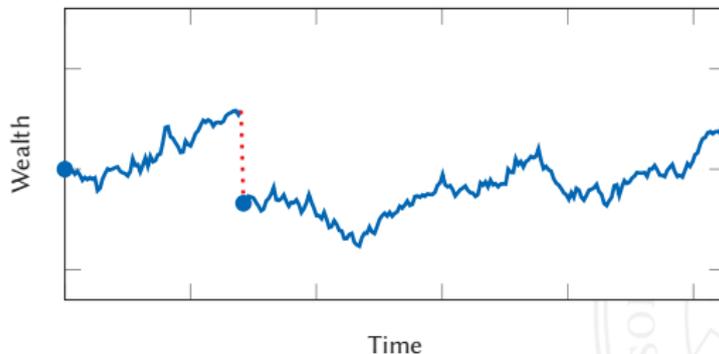


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The General Impulse Control Problem

Consider an \mathbb{R}^n -valued **system** $X = X^\Lambda$ controlled by an **impulse control** $\Lambda = \{(\tau_k, \Delta_k)\}_{k \in \mathbb{N}}$ as follows:

$$\begin{aligned}dX(t) &= \mu(X(t))dt + \sigma(X(t)) dW(t), & t \in [\tau_k, \tau_{k+1}), \\X(\tau_k) &= \Gamma(X(\tau_k^-), \Delta_k),\end{aligned}$$



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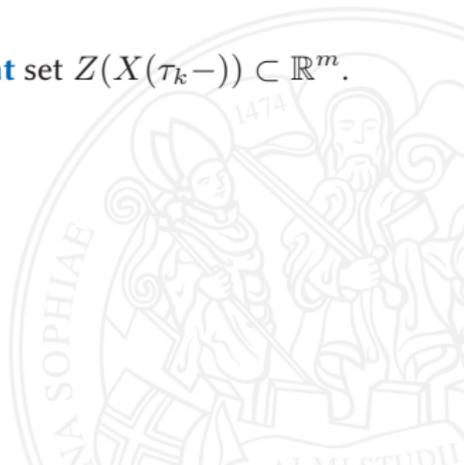
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- the stopping times τ_k are **increasing** and **do not accumulate** in that

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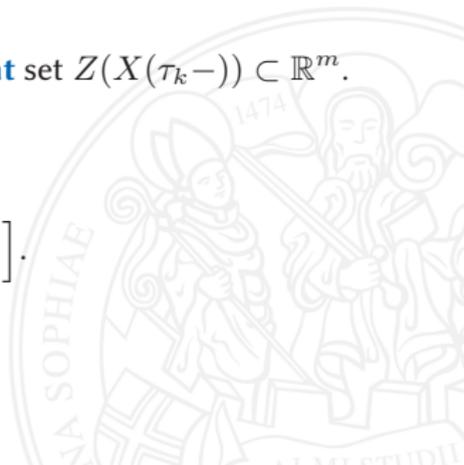
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The **objective** is to find a maximizer of

$$\mathcal{V}(t, x) \triangleq \sup_{\Lambda \in \mathcal{A}(t, x)} \mathbb{E} \left[g(X_{t,x}^\Lambda(T)) \right].$$



A Candidate Optimal Control

Define the so-called **maximum operator** \mathcal{M} via

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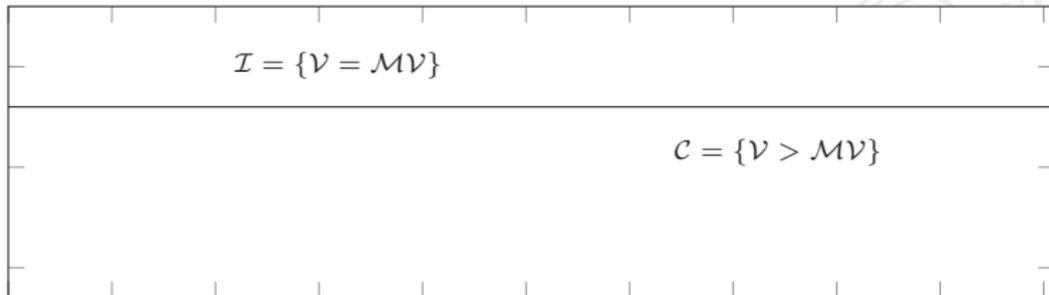
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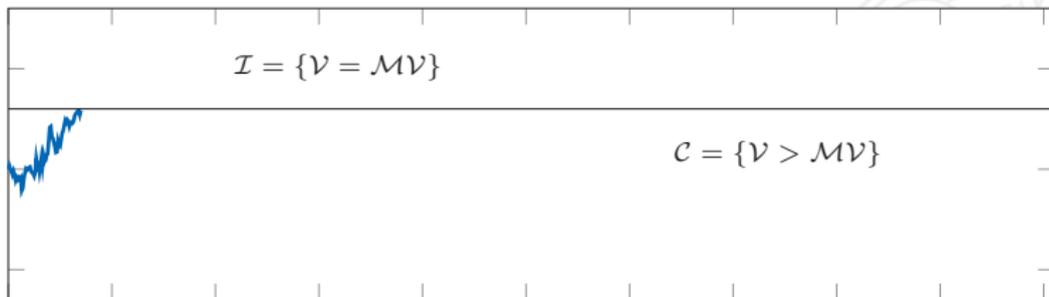
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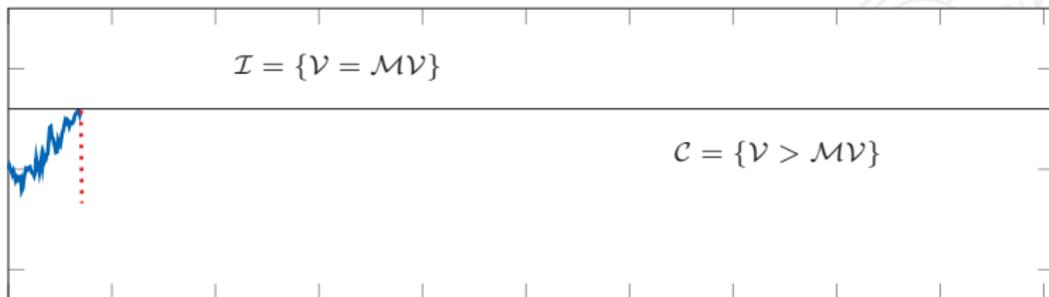
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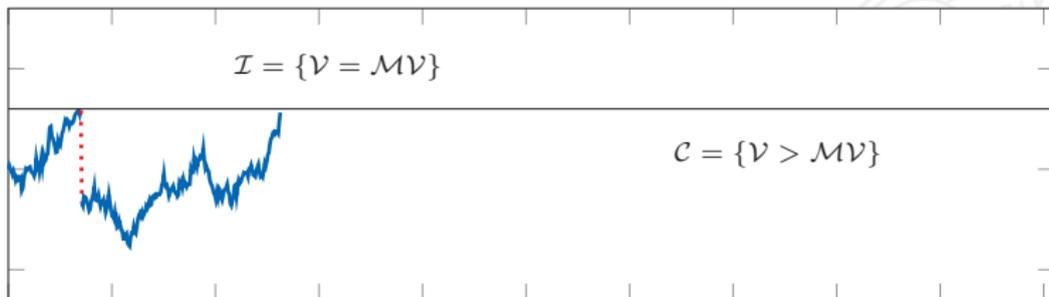
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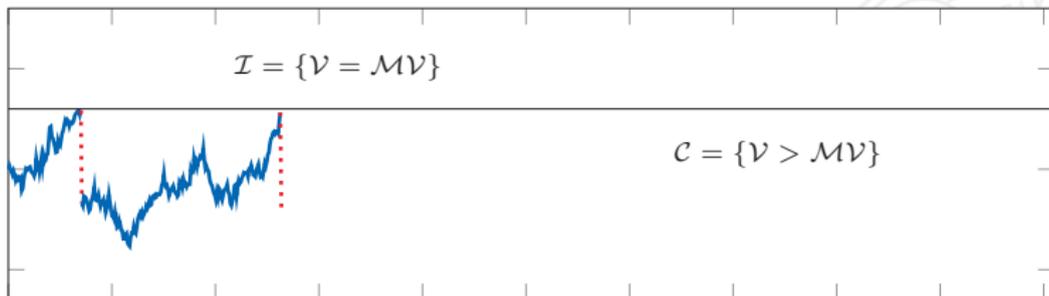
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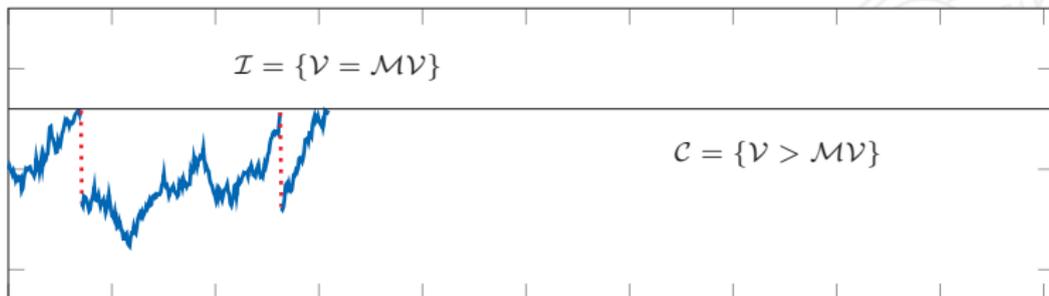
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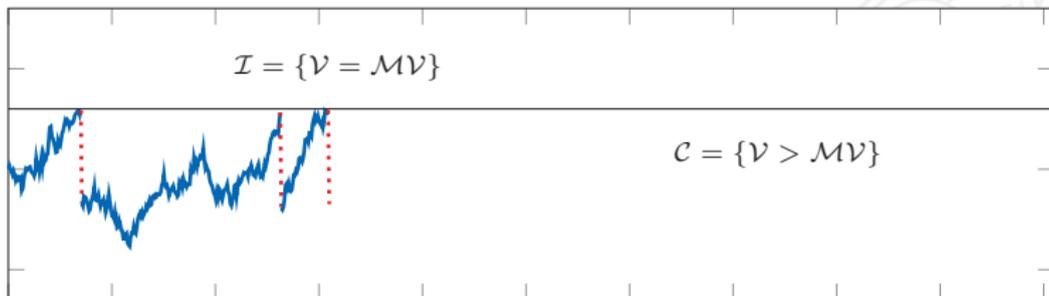
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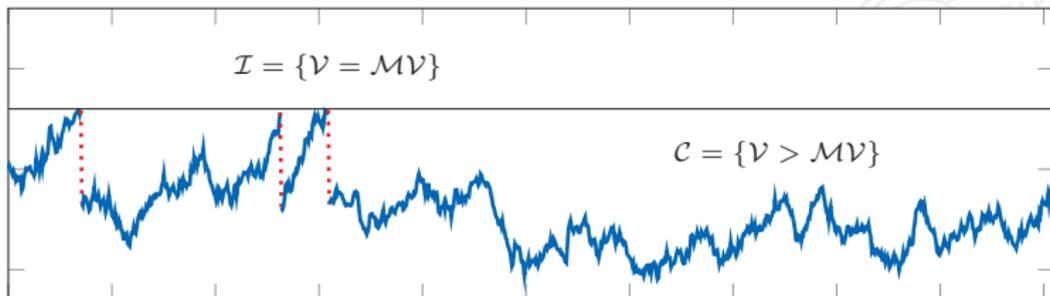
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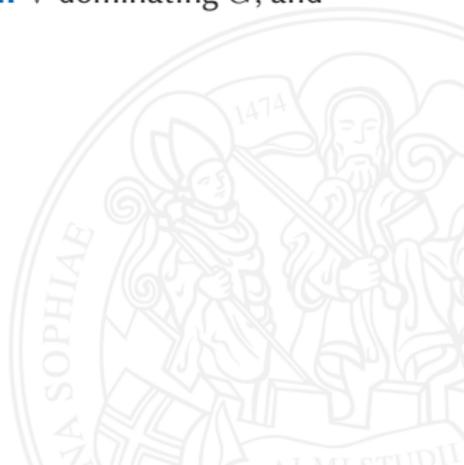
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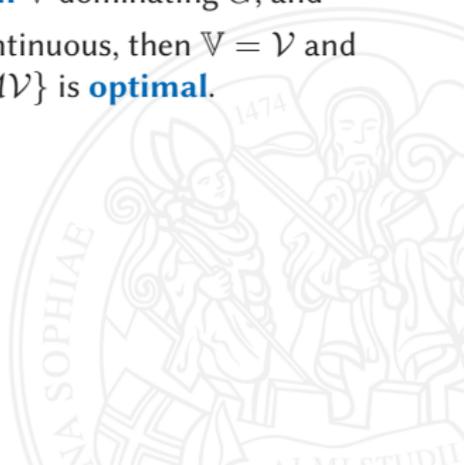
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Remark: Under standard assumptions, \mathcal{M} **preserves semicontinuity**, i.e. $G = \mathcal{M}\mathbb{V}$ is upper semicontinuous if \mathbb{V} is upper semicontinuous. That is, continuity of \mathbb{V} should suffice to solve the problem!

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Proof: Relies mainly on classical optimal stopping techniques, i.e. works in quite general settings.

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$$\begin{aligned} \min\{-\partial_t \mathbb{V}(t, x) - \mathcal{L}\mathbb{V}(t, x), \mathbb{V}(t, x) - \mathcal{M}\mathbb{V}(t, x)\} &= 0 && \text{on } [0, T) \times \mathbb{R}^n, \\ \mathbb{V}(T, x) &= g(x) && \text{on } \mathbb{R}^n, \end{aligned}$$

where \mathcal{L} denotes the **infinitesimal generator** of the uncontrolled state process X .



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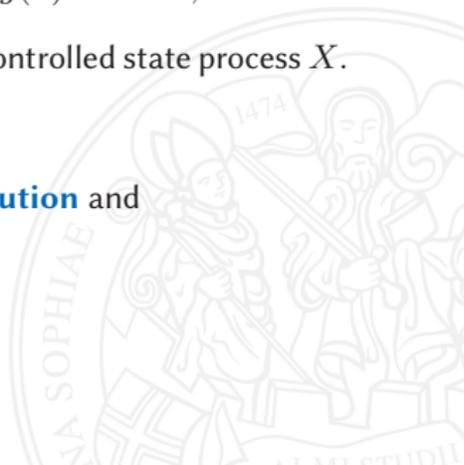
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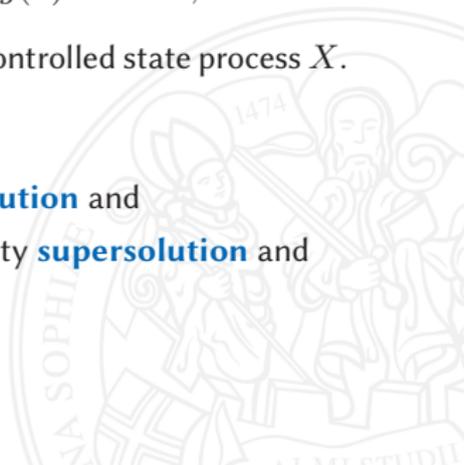
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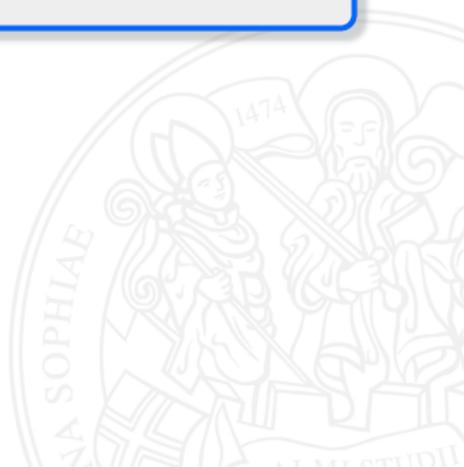
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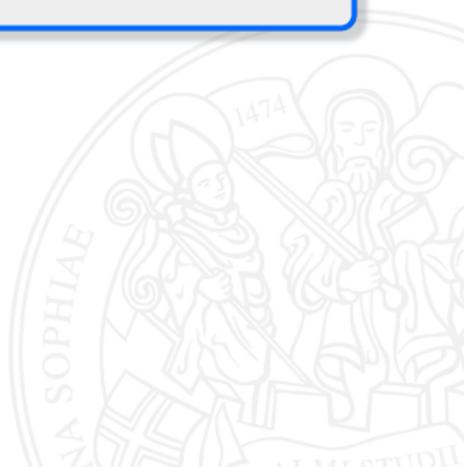


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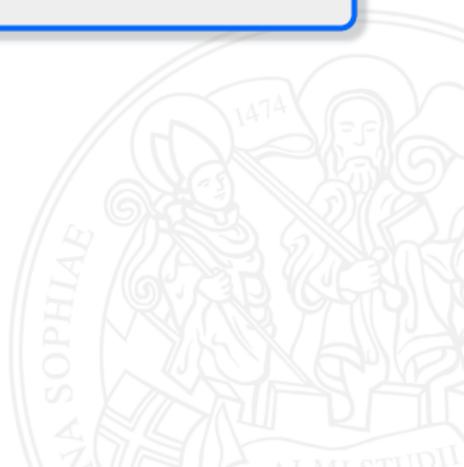


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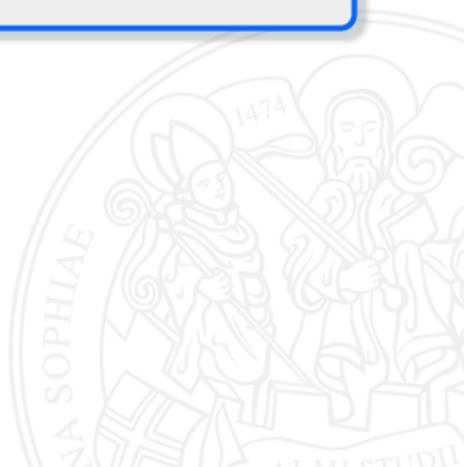


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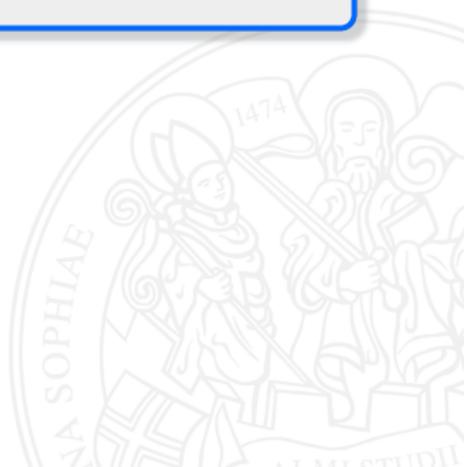
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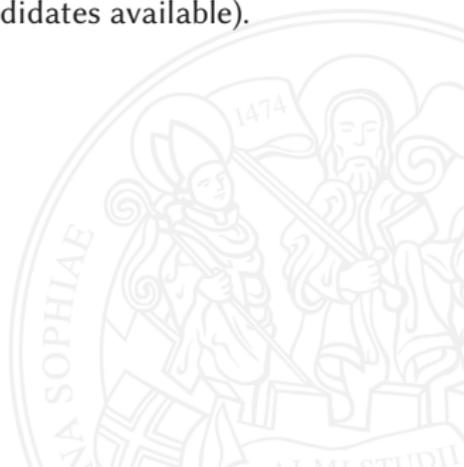
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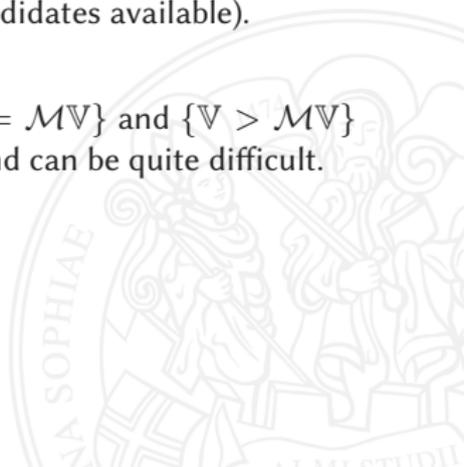
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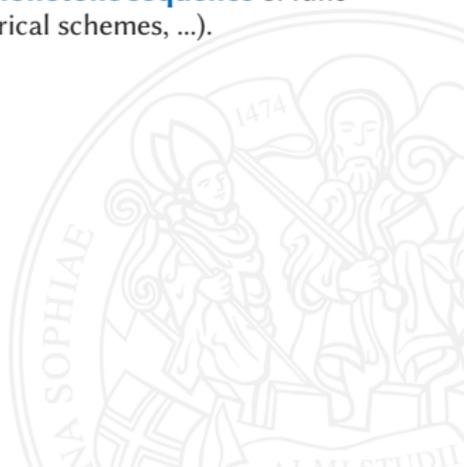
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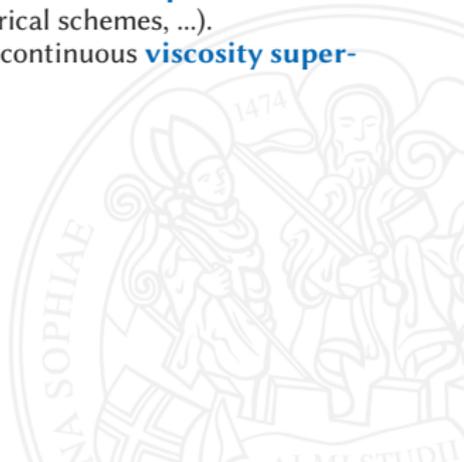
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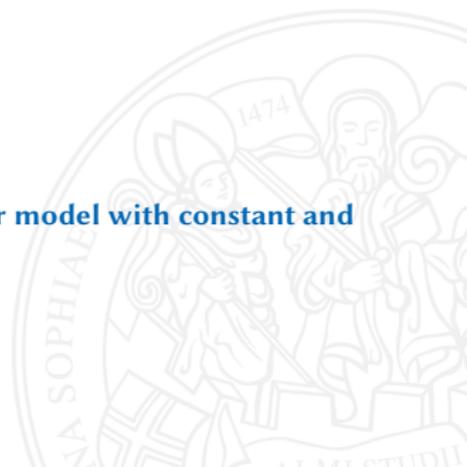
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- How well does this approach work in **practice**, i.e. for specific models?

Utility Maximization with Constant Costs

Based on:

Belak, C. and Christensen, S.: **Utility maximization in a factor model with constant and proportional costs**, Preprint, available on SSRN, 2017.

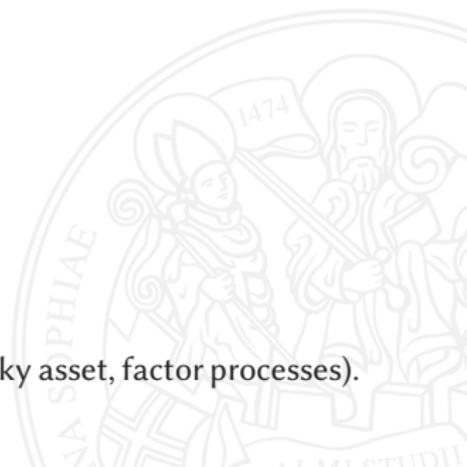


The Market Model

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$$\begin{aligned}dX_1(t) &= rX_1(t)dt, & t \in [\tau^k, \tau^{k+1}), \\dX_2(t) &= \mu X_2(t)dt + \sigma X_2(t)dW(t), & t \in [\tau^k, \tau^{k+1}),\end{aligned}$$

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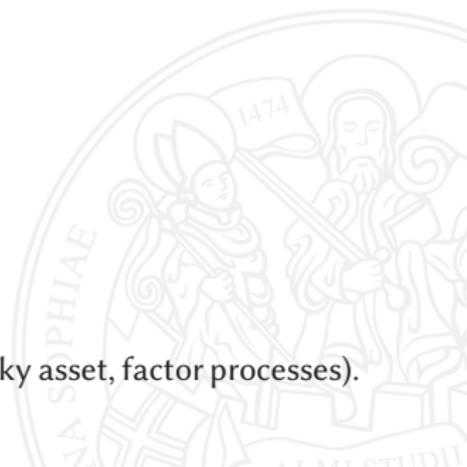
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We **prohibit short selling** of the stock. A portfolio $x \in \mathbb{R} \times [0, \infty)$ is **solvent** if it has a positive liquidation value $L(x)$, i.e.,

$$L(x) \triangleq x_1 + (x_2 - \gamma x_2 - C)^+ > 0.$$

The set $\mathcal{S} \subset \mathbb{R} \times [0, \infty)$ of solvent portfolios is called the **solvency region**.

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The Optimization Criterion

Now fix a **utility function** $U : \mathbb{R}_+ \rightarrow \mathbb{R}$ such that

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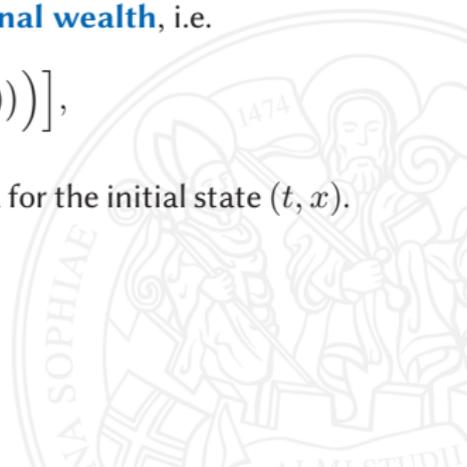
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The objective is to **maximize expected utility of terminal wealth**, i.e.

$$\mathcal{V}(t, x) = \sup_{\Lambda \in \mathcal{A}(t, x)} \mathbb{E} \left[U \left(L(X_{t,x}^\Lambda(T)) \right) \right],$$

where $\mathcal{A}(t, x)$ denotes the set of **admissible strategies** Λ for the initial state (t, x) .



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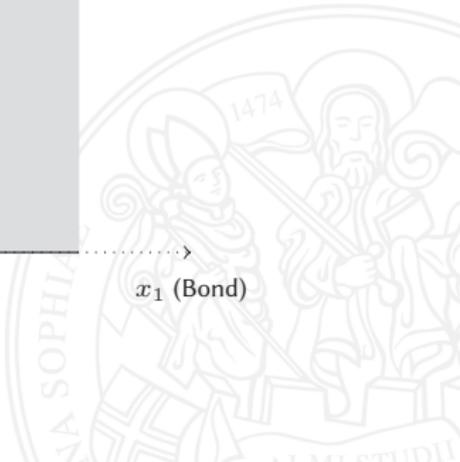
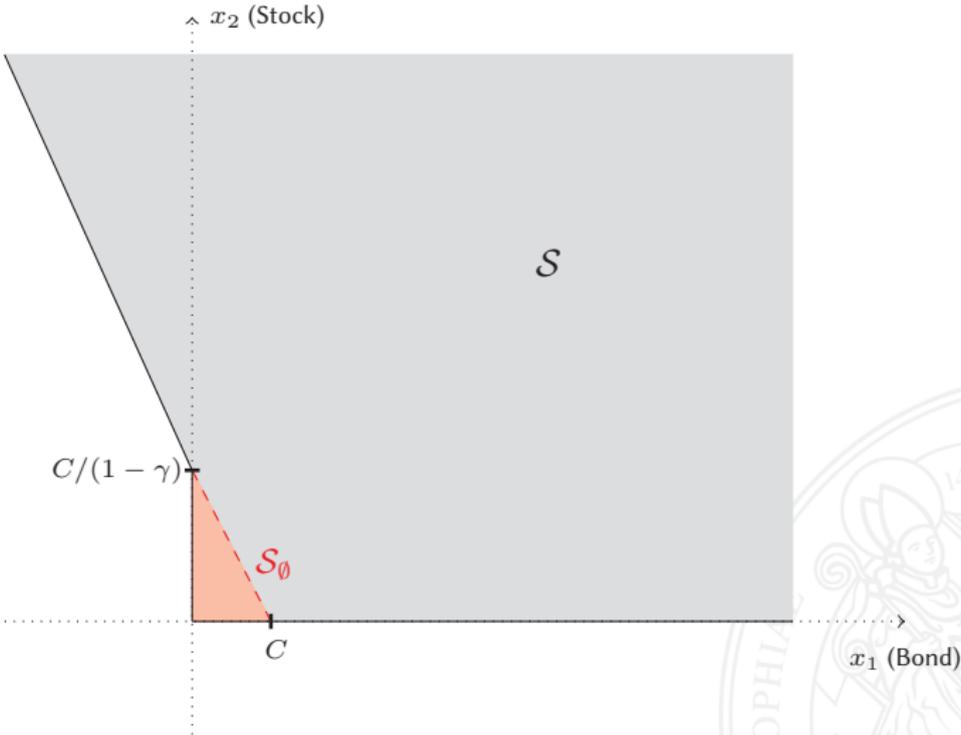
- ... the **state space is constrained** to \mathcal{S} instead of all of \mathbb{R}^2 , meaning we face additional boundary conditions on $\partial\mathcal{S}$.
- ... the set of transactions may be **empty**, the maximum operator \mathcal{M} does not preserve **semicontinuity** everywhere.
- ... the value function is **discontinuous**!



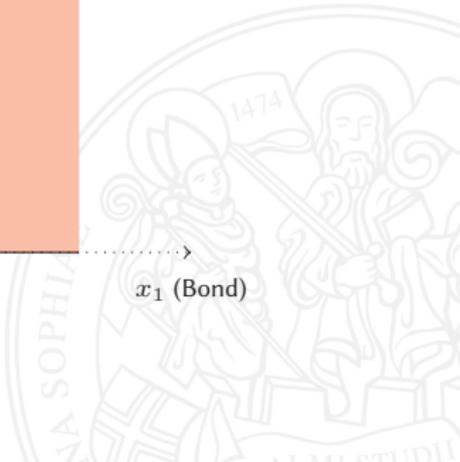
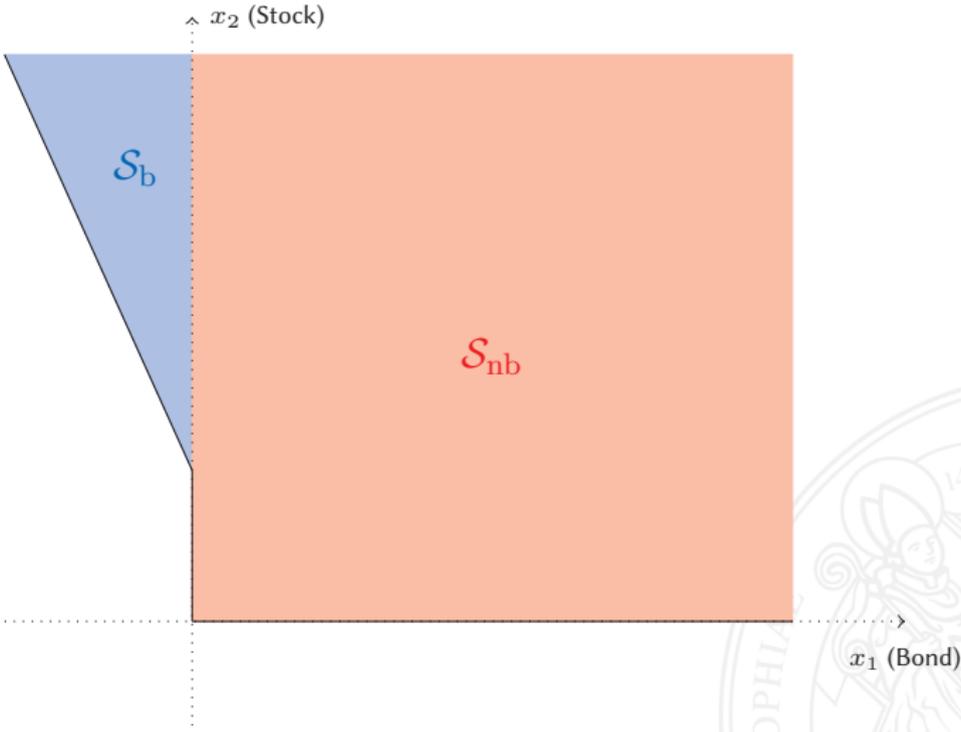
(Dis-)Continuity of the Value Function



The Solvency Region



Localizing the Solvency Region



The Local Comparison Principle

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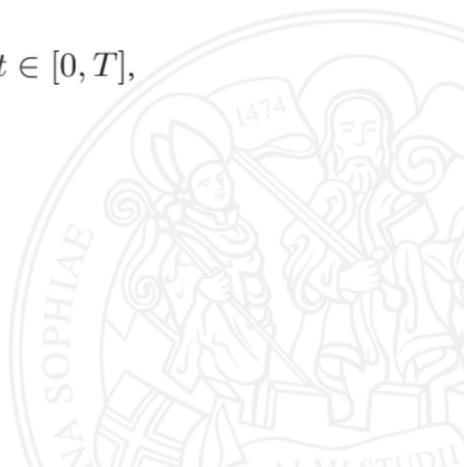


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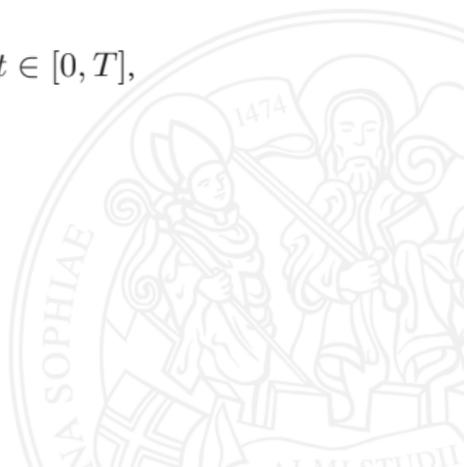


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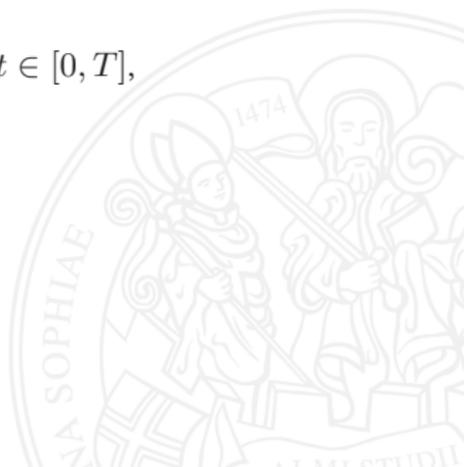
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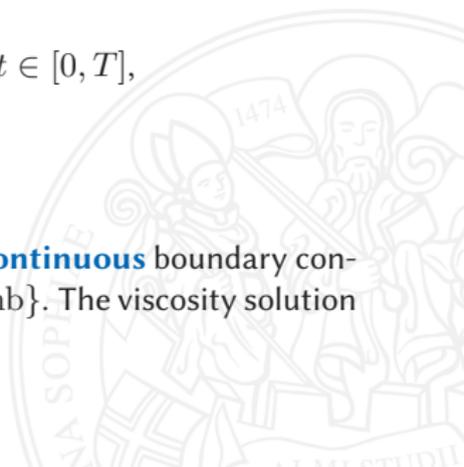
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This implies that any viscosity solution with **piecewise continuous** boundary condition is **continuous if restricted** to $[0, T] \times \mathcal{S}_\circ$, $\circ \in \{b, nb\}$. The viscosity solution need **not** be globally continuous.



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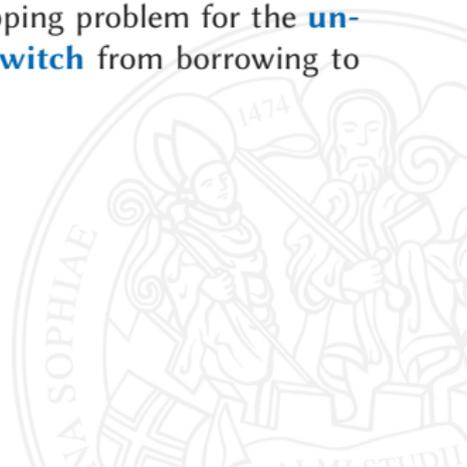
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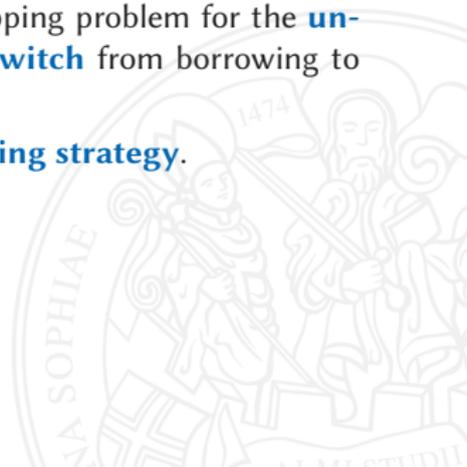
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- With this, we are able to construct an **optimal trading strategy**.



Conclusion

- **Aim:** Solve a portfolio optimization problem involving constant costs.



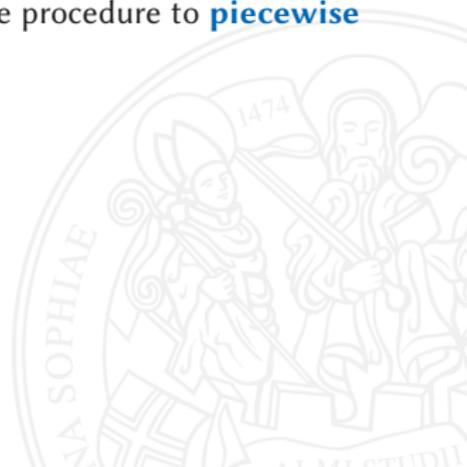
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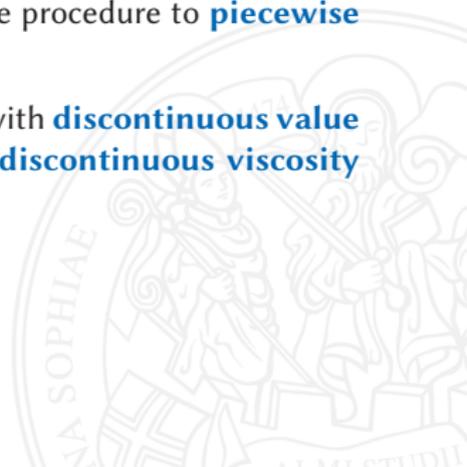
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Thanks for your attention and enjoy the coffee break!

Optimal Trading Regions

